

Apparel Fit Language Suited to 3D Body Processing Ecosystems

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Abstract

Colloquial language, reflective of the diversity of practitioners involved in 3D Body Processing (3DBP), has proven to be an obstacle toward shared digitization efforts. Here we distill language specific to apparel manufacturing for clarity toward the shared goals of the 3DBP ecosystem. The whitepaper "3D Body Processing Ecosystem Overview" simplified the processes within the 3DBP ecosystem using four assets: cover, coveroid, human, and humanoid. From this we understand a cover to be any product, garment, or material worn on a human and a coveroid and humanoid to be the models of the finished forms. Here we build upon this foundation to consider where language fails to provide clarity crossing the physical to virtual realms within the 3DBP ecosystem. Through this discussion, apparel challenges are highlighted from both the perspective of the apparel practitioner (requiring subjective, heuristic, sensory processes) and the software architect (requiring objective, logical processes). Perspectives on fit are provided clarity for future dialogue toward cross-platform solutions suited to the 3DBP ecosystem. The terms are applicable beyond the influence of current trends or style aesthetics and therefore scalable, relevant to well established manufacturing practices, yet sensitive to the art of garment design which is, and will remain, foundational to apparel practice.

Keywords: garment fit, fit, 4D fit, fit assessment, fit mapping, 3DBP ecosystem, humanoid, coveroid

1. Introduction

Discussion herein considers apparel fit language suited to both physical and digital space apparel practice with the goal to engage conversation toward a larger treatise for a thorough dissemination of apparel fit language. Terminology will reference the four assets summarizing processes within the 3DBP ecosystem where the term humanoid is understood to be any representation of a human, cover is understood to be any body-worn product, and coveroid is any representation of a cover. As the act of modelling humans and covers is established apparel practice, the terms humanoid and coveroid can be understood to be models (representations) of physical objects in either physical or digital space. The term cover includes all finished body worn products including molded products and wearables (body-worn products meant to monitor the bio-chemical activity of the wearer). Covers for consumers or wearers (humans) are developed on models (humanoids) as test samples (coveroids). [1]

This paper will discuss apparel fit terminology to ensure definitions bridge the physical to digital realms concerning the following areas of discussion.

1. Humans and Humanoids Body Data
2. Covers and Coveroid Geometry
3. Cover and Coveroid Sizing
4. Human-to-Cover and Humanoid-to-Coveroid Interaction - Fit Assessment

2. Terminology

2.1. Human and Humanoid Body Data

3D Humanoids

A humanoid is any representation of the human used for product development. 3D humanoids can be created from real or synthetic human body data (see below). There are numerous methods available for both booth scanners and photogrammetry scanning apps.

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2.1.1 - 1D Humanoids (Measurement Data)

In both physical and virtual space apparel environments the measurement data set, used to create covers, exists as a 1D representation of the human. Human body data (measurements) are acquired either heuristically (using visual landmarking cues and honed technique), using known anthropometric process [2][3][4], algorithmically using proprietary devices in physical environments[5], or using extraction software in virtual environments. Measurements can be generalized as horizontal girths and vertical lengths taken as either surface dimensions (closely following body contours) or linear dimensions (straight-line distances between landmarks). In virtual space practice measurements are observed on 2D cross-sections. In virtual environments, split-lines direct cross-sectional planes from which measurements are retrieved as perimeter distances, girths, or linear dimensions.

2.1.2 - 2D Humanoids (2D Body-Shape)

In virtual environments, the 3D humanoid may be flattened (UV unwrapping) for a 2D humanoid model. Considering a humanoid may be flattened we can begin to imagine that a quantification of body-shape as a coveroid is possible. A flattened humanoid, however, is not directly usable within traditional apparel pattern-engineering practice. Just as the 1D and 2D dimensions of a sphere will vary, so too will the 1D and 2D dimensions of human body-shape vary. For 2D flattened humanoid geometry to be suitable for use as a developable pattern (suitable for manufacture) shaping devices (see below) must be added. Efforts to systemize this process for direct link to apparel CAD are ongoing.[6] [7]

2.1.3 Static Humanoids

A static humanoid is concerned with only a single moment in time. In physical space, dress forms (used for fitting and sampling), and mannequins (used for display) are examples of static humanoids. In virtual space, static humanoids exist as real (scanned human body) or a statistically generated humanoid body data (generated from population data).

2.1.4 Rigged Humanoids

Since a single moment-in-time static does not fully capture the breathing and constantly changing nature of human morphology, dynamic models are used in both virtual and physical space for 4D testing of cover and coveroid products. In physical environments fit models are used for 4D fittings involving motion. In virtual environments humanoids may be provided a virtual skeleton (rig) for simulating human movement.

2.1.5 Statistical Humanoid Data

Humanoids can be generated from statistical data (the averaging of left and right sides). To better represent the dynamic nature of human bodies, measurement data gathered from several days or from several scans may be statistically compiled for a more accurate representation of the human.

2.1.6 Synthetic Humanoid Data

Synthetic humanoid data are compiled from population or demographic data. Such data forms the basis of size charts. In physical space this data is used to create mannequins. In digital space, humanoids can be parametrically generated from such data.

2.1.7 Body Segments

Body segments, sometimes referred to as patches, identify body areas between two joint landmarks. For example, the leg is divided into upper and lower segments by the hip, knee, and ankle landmarks. Coveroid pattern geometry (blocks) also reference these same body segments. Base body segments, reflective of the skeleton and coveroid pattern geometry are head, neck, arms, hands, mid torso, lower torso, legs, and feet. Since human shape is complex, segments are further sub-divided into regions for detailed analysis of morphology. [8]

2.1.8 Skeletal Landmarks

Skeletal joint landmarks denoting body segments are common to standards simulating humanoids [9], discussing digital fittings [8], body measurements for apparel [3], and human dimensions for ergonomics [10]. Skeletal landmarks denote joints critical for movement considerations in both humanoid and coveroid. The humanoid must be provided a virtual skeleton (rig) directed by joints so human motion may be simulated.[11] Since coveroid geometry must provide movement allowance (ease) where bones meet and bend during motionjoint landmarks are as critical to the coveroid as humanoid. Indeed, these landmarks lay the foundation for humanoid-to-coveroid mapping practice. [12] (*NOTE* citation relates to online studio access portion of textbook*)

2.1.9 Morphological Landmarks

Morphological points denote surface anatomy known to identify uniqueness of human form within the body segments. For example, the bust and thigh landmarks identify uniqueness around which sizing systems are developed. Product specific landmarks, such as those required for an angled waist, [13] can also be referenced.

2.1.10 Landmarks

Landmarks rest as the foundation of any mapping system. Within the 3DBP ecosystem they rest as the base point of reference between the four assets. Technologies concerned with humanoid data sometimes refer to these points as feature points. Barring missing anatomy, landmarks identify reference points considered common to all humans. In physical environments landmarks are heuristically located using intuitive visual clues. In virtual environments algorithms are used to assign Cartesian coordinate points of reference: the x co-ordinate reference width points left to right (lateral or medial) on the body, the y co-ordinate reference height points from top to bottom (superior to inferior) on the body, and the z co-ordinate references depth points from front to back (anterior to posterior) on the body.

2.1.11 Static Landmarks

When observing the body in 4D (over time or through a range of movements) it is helpful to identify landmarks that will remain static. Due to the malleable nature of human flesh, no point can truly be considered static. 4D study in virtual environments, however, offers the opportunity for static surface (skin) landmarks to remain attached to the rigged skeleton for unique study of changes to human shape not practical in physical environments. Study here is ongoing.

2.1.12 Split-Lines

Split-lines connect landmarks as either lines or arcs to denote body segments as patch boundaries

2.1.13 Humanoid as Coveroid

A strong correlation exists between body segments and garment patterns but, the process of flattening a humanoid (UV unwrapping to create a 2D humanoid) for use as a coveroid has proven problematic. Technically, a humanoid provided split lines to denote patch boundaries can then be flattened to reveal an unassembled coveroid. While effective methods for flattening complex morphology exist, these methods do not adhere to foundational principles of garment pattern creation.[14] Consequently, utilizing the humanoid as coveroid has application limited to mainly molded product common with wearable products.

2.1.14 - 3D Cross-Sectional Planes

3D cross-sectional planes reveal girths and lengths from the 3D humanoid as planar volumes for a unique perspective not possible in physical practice. Usually, split lines will direct horizontal or vertical cross-sectional planes, but shaped planes are also possible.

2.1.15 - 1D Dimensions

In physical space practice measurements are retrieved with a tape-measure. These measurements, taken from a 3D body in both physical and virtual practice, are referred to as 1D dimensions.

2.1.16 - 3D Dimensions

In virtual space practice measurements are retrieved from cross sectional planes revealing a 3D volumetric slice of the humanoid.

2.1.17 - 2D Dimensions

Equally important, and the reason a flattened humanoid cannot directly be used as a coveroid, are 2D dimensions. While there exists a strong correlation between 1D dimensions and 3D dimensions, this correlation does not hold true for 2D pattern dimensions. The reason for this is best explained with reference to 2D cube and sphere patterns. While the height of a cube pattern may quite simply be represented as four times the height of one side, the height of a sphere pattern is not so easily explained. Just as a sphere is a non-developable surface not easily translated to 2D dimensions so too are humanoids considered non-developable.

2.2. Covers and Coveroid Geometry

2.2.1 Unassembled Cover or Coveroid

While it is possible for covers to be manufactured as single piece molded products it is more common for products to consist of pieces which must be joined together. Therefore, both a cover and coveroid may exist in both an unassembled and assembled form.

2.2.2 Pattern

The unassembled cover or coveroid can be referred to as a pattern. In most instances, the pattern is comprised of multiple pattern pieces. In physical space, the unassembled coveroid is cut from geometric shapes (templates) referred to as patterns. In digital space since material properties (colour, print, texture, physics of drape) may be applied directly to the pattern template piece(s), there is no distinction between the pattern and the unassembled coveroid. In digital space the pattern itself is an unassembled coveroid becoming an assembled cover or coveroid when the pattern pieces are joined (sewn or welded) to form a 3D object. In physical space, the template block is used to cut material shapes prior to joining. This additional step plus the use of materials makes sampling (see below) more economical in digital space. Patterns have a direct correlation to critical landmarks denoting body segments.

2.2.3 Block

The term block references a base pattern from which other patterns may be derived to create a hierarchy (see below) of patterns with the same established fit.

2.2.4 Pattern-Engineering

Pattern-engineering includes any practice related to the creating of cover or coveroid patterns, including draping, drafting, computer aided design (CAD), and grading. Sometimes referred to as pattern cutting, pattern creation, patternmaking, and pattern-drafting, here we have chosen the word pattern-engineering to respect the high degree of technicality 3D technologies bring to the craft of constructing patterns for coveroids and covers.

2.2.5 Draping

Draping is an artisanal heuristic technique using visual and tactile cues to form fabric to body. [12] Methods to replicate this practice in virtual environments are less tactile and more geometric than physical practice [15] but augmented reality environments could change this.

2.2.6 Drafting

Drafting uses principles of Euclidean geometry to map humanoid measurements to the unassembled coveroid pattern.

2.2.7 Computer Aided Design (CAD)

CAD patternmaking takes place in a digital environment. In 3D-to-2D CAD environments a template block, or template block pieces, are virtually draped to a humanoid form. In 2D-to-3D CAD environments a template block is created using pattern drafting technique and then virtually sewn and wrapped around a humanoid for test fitting (sampling). [16] While any of the above techniques may be used repeatedly for pattern creation, the reuse of garment patterns is a common shortcut. Any pattern created through the above methods may become a block and form the foundation for an extensive hierarchy of parent-child family patterns.

2.2.8 Grading and Parameterization

Grading is an apparel specific parameterization process for resizing a base size cover or coveroid pattern to create sizes both smaller and larger. [17] The process is directed by grade rules for the offsetting of pattern perimeter lines but darts, whether visible or hidden within pattern geometry, are not graded (see body-shape parameterization). Since shaping devices define body shape, the offsetting of perimeter lines effectively creates smaller and larger sizes of the same body-shape. The assumption with grading is that fit tolerance (see below) can be utilized to accommodate other body-shapes with similar humanoid data sets. A percentage of outlier body-shapes is expected. While machining industries provide example of the parameterization of complex shapes such methods lack applicability to apparel products [18] where fabric grain must be considered relative to individual morphology. Unique attributes of body-shape are often difficult to accommodate within the traditional grading process. Research toward established practice for grading patch seamlines and darts specific to body shape are ongoing. [19] Further, since garment design relies heavily on the manipulation of darts and seams, shaping devices are often hidden within garment pattern architecture and obscured from grading consideration. That patternmaking practice is founded on the categorization of humans into shape categories (e.g., infant, child, female adult, male adult) speaks to the inherent limitations within traditional CAD parameterization engines.

2.2.9 Posture

The effect of posture on 2D body-shape (as pattern geometry) is difficult to study in physical environments. Most covers and coveroids are suspended from the shoulders or hips, and therefore posture (e.g., the slope of the shoulders or angle of the pelvis) will affect the fit relationship between the cover and the human resulting in a balanced or unbalanced cover. While it has been demonstrated that posture effects measurements [20], study as to why continues. Dimensional change may possibly be attributed to a change in shaping device requirements (body-shape) or attributed to functional ease requirements. [21] Virtual environments will be pivotal toward further study. Cross-sectional analysis of planar girths in virtual environments permits a unique perspective of the body as a series of stacked planes for further study of the effects of posture and gravity on pattern geometry.

2.2.10 Shaping Devices

Shaping devices are seamlines and origami like folds (darting) added to garment patterns so cover and coveroid material may be shaped to human and humanoid form using the principles of fit (see below)[22]. When a contoured fit is desired (no ease), shaping devices account for the dimensional variation between 1D and 2D dimensions which define 2D body-shape (see below). When creating blocks with ease, consideration for shaping devices directs the distribution of ease. Darts are internal lines indicating where internal dimension must be removed to mold material to morphology. [23] Seams reflect the boundaries of the pattern pieces which are inherently related to the split-lines connecting landmarks. Of importance to note, the precise location of shaping devices is dependent on practitioner preference. Consequently, two practitioners could achieve the same assembled coveroid geometry through varied application of darts and seams [24].

2.2.11 Pattern Manipulation

Maintaining the fit of the parent block through the building of pattern hierarchies is reliant on established practices for the manipulation of shaping devices. Seams may be eliminated by joining pattern pieces, created by adding new split-lines (see above) in the patterns, moved by removing dimensions from one pattern piece and adding it to another connecting piece, or changed by adding ease dimension. Darts

may be increased in size to remove dimension, decreased in size to add dimension, or manipulated and hidden with the style lines and pattern geometry. The hiding of darts within style lines is inhibitive to both parameterization and size selection applications.[25]

2.2.12 Truing

Truing is the process of smoothing lines and curves between critical landmarks. Traditional manual practice relies on heuristic technique utilizing rulers and French curves. By defining geometric relationships [26] between patch boundaries (mathematical concepts of tangency and continuity) constrained splines can be derived to better define the mathematical relationship of the line or curve to surrounding pattern geometry.

2.2.13 Pattern Hierarchies

Base blocks are often referred to as parent blocks reflecting their infinite reuse within a family hierarchy: child, grandchild, great-grandchild etc. In general, a parent block (sometimes called a template block, block, sloper) defines a fit for a given style. For example, the template block for a tight-fitting jean and a pleated trouser would be very different. The parent blocks for the tight-fitting jean and pleated trouser could be used to derive multiple grandchild and great-grandchild blocks. In physical environments it is difficult to maintain the fit data established with the parent block through the reuse of patterns. In virtual environments, much opportunity exists to trace the original parent block fit through multiple pattern iterations.

2.2.43 Principles of Fit

Parent blocks, and derivative family block patterns, are developed using the established principles of fit [27] and/or numerous reinterpretations of these principles.[28] ***Using the principles of grain, set, line, and balance shaping devices are used to distribute ease suitable for a chosen style.*** Due to the complexities of fit and the dynamic nature of human form, it is highly likely compromise, directed by a cover's primary function, will be required. For example, length ease required to bend over and touch one's toes may appear excessive when standing but be required if a cover's purpose is for a predominantly bent position. When making fit decision compromises, test fitting and sampling (see below) are integral the pattern-engineering process.

2.2.15 Sampling

Sampling refers to the process of testing the production process, product quality, and product fit. During the process of sampling a tech pack (see below) will be created, updated, and modified until a final design, material(s) choice, and process has been deemed suitable.

2.2.16 Tech Pack

Accompanying all unassembled coveroids is a set of instructions commonly referred to as a tech pack. Product dimensions and humanoid dimensions are an important component of the tech pack as these details are used for fit mapping and size selection. Tech pack data may also be linked to PLM (product life management) systems to direct ordering of product materials. (e.g., fabric, thread, interfacing, interlinings, linings, buttons, zippers, etc.) Ideally, the tech pack provides sufficient instruction for the unassembled cover or coveroid such that it can direct identical product development at manufacturing facilities of the same caliber. Since minor manufacturing error is expected, the tech pack also serves as guide to against which to gauge acceptable manufacturing fit tolerance (see above).

2.3. Cover and Coveroid Sizing

2.3.1 Key Measurements

Key measurements identify dimensions of primary concern in cover or coveroid production, labelling and size selection.[29] Due to the complexity of human form, such measurements are often used within hierarchies for the sub-classification of human morphology suitable for product development. For example, height is frequently used to sub-classify demographic data into age related categories of infant, toddler, child, youth, adult. A subsequent waist girth identifies change between sizes. Subsequent key measurements could be used to identify body-shape relevant to product. For example, a hip girth

indicates a drop value related to lower torso body-shape while an inseam length identifies torso and leg as ratios to height. Key measurements are most often related to skeletal landmarks (feature points)

2.3.2 Fit Mapping

Fit Mapping identifies a process used for grouping demographic data into sub-categories based on a desired incremental change of a key measurement (see above) and with close regard for a hierarchy of related body dimensions. It is used to initiate a sizing strategy, and then used in reverse to match human or humanoid body dimensions to cover or coveroid sizing. For example, age (baby, toddler, girls, boys, adult) and height (petite, regular, tall) are common first tier sub-categories. Due to the complexity of human form, further nested sub-categories to generalize fit areas of concern will be required to optimize product development. For example, lower torso shape [30] may be used as sub-categories for fit mapping. Digital technologies have been pivotal in parsing complex interconnected factors affecting fit mapping with efforts for improved body-shape analysis ongoing.

2.3.3 Sizing Systems

Sizing Systems generate dimensional rules for covers and coveroids around key measurements and to accommodate common size groups highlighted with fit mapping. For example, a common key measurement for North American blue jeans is the waist with an incremental change of 5cm (or 2 inches). The related hierarchy of body dimensions is age (adult), gender (male/female), height (petite/regular/tall), key or primary girth measurement (waist girth), secondary measurement (inseam), tertiary measurement (thigh girth). [29] Critical to any sizing system strategy are the rules for incremental change (grade rules or grading) which define individual sizes, connect them as a system and are used to link human and humanoid to cover and coveroid product. Grading is the heart of any sizing system.

2.3.4 Fit Tolerance

Fit tolerance may be considered from the perspective of an individual (**individual fit tolerance**), the perspective of a size category (**size fit tolerance**), or the perspective of affectable manufacturing error. In both instances 4D fittings are imperative. For example, a cover may have an intended fit of 10cm of hip ease but be considered suitable on humans with hips both 2.5cm smaller (where it would be slightly large) and larger (where it may be slightly small). Similarly, a cover constructed in stretch material can stretch less or more to respectively accommodate body-shape variation smaller or larger. **Manufacturing fit tolerance** considers the degree to which an assembled cover may vary from sampled (see above) product specification. Tech packs, detailing assembled cover dimensions, play an integral role in assessing manufacturing fit tolerance. Fit tolerance may be seen as in contrast to fit optimization and decisions must be made as to whether to compromise optimum fit against fit tolerance.

2.3.5 Fit Intent

Fit intent attempts to define a designer's vision of the body-to-garment interaction. Material (most usually fabric) is a critical factor in this vision. Beyond this, words such as tight, semi-fitted, fitted, loose, relaxed, tailored etc. would be used to evoke an understanding of fit. Much effort has been directed at associating mathematical values to terms commonly used to define fit.[28] [31] Practice, however, continues to favour language suited to current trend over numerical fact. This non-qualitative approach to fit assessment may very well play a large role in garment returns as customers may have a differing opinion on the mathematical values associated with descriptors such as tight, fitted loose. It may also play a role in misapplication of machine learned fit preference leading to human dissatisfaction with customized product.

2.4. Fit Assessment

2.4 1 - 3D Fitting

Since fitting refers to the process of trying on the cover or coveroid it is intrinsically linked to sampling. A 3D fitting transpires on a static humanoid. In physical practice, fit tolerance considerations are made when test-fitting a manufactured sample cover. In virtual practice, fit tolerance considerations can be made without the costs associated with physical sampling (material and production costs). Both physical and virtual space practice suffer from problems associated with fit validation where fit data can be

understood as geometric dimension against a baseline from which its accuracy can be understood. [32][33][34]

2.4.2 - 4D Fitting

Since a static humanoid does not adequately represent the dynamic nature of humans, 4D fittings transpire on humanoids capable of movement through a range of movements. Such fittings consider the fit of a garment over time and through a range of movements.[35] [36] For example, by testing the fit of pants in a seated as well as standing position. In physical space practice this can involve robotic dress forms or human fit models. To test **individual fit tolerance**, a coveroid must be tested on the same humanoid from which the 1D humanoid dimensions for coveroid generation were acquired. To test **size fit tolerance**, the fit model humanoids used for fit testing will have dimensional variation from the 1D humanoid data used for coveroid generation but would still fall within the same size category. In other words, the 2D pattern geometry representing shaping devices of the fit models would vary from the base size used for coveroid generation.

2.4.3 - 1D Fit Assessment

Traditional fit assessment practice has favoured 1D fit assessments comparing how 1D sizing system measurements vary from 1D human or humanoid measurements. Sizing system dimensions do not always have a direct correlation to garment (or garment pattern) dimensions. Hence, a 1D fit assessment is suitable for narrowing scope of garment selection, but not effective for critical fit assessment decisions involving shaping devices. Nor for considering how wearer and brand fit preference may align.

2.4.4 - 3D Fit Assessment

Virtual approaches to fit assessment consider the interaction of body-to-garment as pressure on the humanoid by the coveroid, or as radial ease considering how and where the coveroid is offset from the humanoid. [37] Methods to translate this sensory data to pattern geometry as fit parameters are ongoing. For example, a high degree of pressure indicates zero to negative ease while minimal pressure indicates positive ease.

2.4.5 Sensory Fit Assessment

A sensory fit assessment is a subjective assessment based on sensory response. Sensory fit considers a user's, often subconscious, sensory response to a cover or coveroid. [38] Involving a multiplicity of constantly evolving decisions, strongly driven by seasonal trend, machine learning has been critical in collecting fit preference data (see below).

2.4.6 Machine Learned (ML) Fit Assessment

Machine learning has been pivotal toward collection of fit data, which is often linked to emotive, intuitive, responses. A machine learned (ML) fit assessment collects data regarding customer cover buying decisions, aesthetic preference, and sensory preference, to predict future cover buying decisions and preference for fit utilizing computer algorithms. Such data is extremely useful for determining customer fit preference. Efforts for application of machine learned fit preference suitable for application to production pattern are ongoing.

2.4.7 - 2D Fit Assessment

Any assessment regarding fit must speak to cover or coveroid geometric dimension for assigning of size or correcting of perceived fit. Therefore, regardless of fit assessment method used, acquired fit data must be translated to 2D geometric dimensions suitable for comparison to either the assembled or unassembled cover or coveroid. A 2D fit assessment may be accomplished heuristically (hand forming material to body) or algorithmically (translating compression of radial ease to pattern geometry). To effectively change cover or coveroid fit, either a post-production alteration to the assembled cover, or a pre-production change to the unassembled cover or coveroid is required. Efforts are ongoing for automation to direct change at the developable garment pattern level for quantified fit and mass customization of cover products. Effort toward translating acquired fit data to drive or alter pattern engineering process are ongoing. Where early methods failed to recognize established principles of fit or dart manipulation theory [39], apparel engineers building on this early work are making headway. [6]

3. Discussion

Apparel digitization has been an arduous journey requiring the blending of artistic endeavor and engineering. Language common to one end of the 3DBP ecosystem spectrum has been confusing to the opposing end. Considering the assets and transformations within the 3D body processing ecosystem and the fit terms discussed herein offers clarity toward understanding the data involved in any given fit situation.

3.1. Considering the Future for Human and Humanoid Body Data

The 3D humanoid data rests as the ground truth for body dimensions. Joint landmarks partition the 3D humanoid into segments related to apparel blocks and for the measuring of 1D humanoid dimensional data sets.

From here coveroid development can be consider from posing the question ‘what modifications to human or humanoid dimensions can achieve the desired cover or coveroid outcome.’ Whilst fit is complex, it can be hypothesized that the human-to-cover relationship may be numerically expressed as a difference in dimensions between the cover and human, or coveroid and humanoid. How the variables of fit contribute to this is a matter for wider research, but a numeric value of difference is the hypothesized outcome to be operational in real or virtual environments. From this perspective the possibility for reverse engineering a cover or coveroid for mathematically quantified fit is presented and apparel fit challenges can be imagined from a perspective of computer architecture yet within the bounds of traditional artistic endeavour of cover design.

Assuming the above, the first step is to ask, ‘what is added to the flattened 2D humanoid data to make it suitable as a developable coveroid pattern.’ These dimensions represent shaping devices. Combining 1D humanoid data with shaping device data provides a unique opportunity for the possibility of quantifying body-shape as 2D geometric dimension.

3.2. Considering the Future for Cover and Coveroid Geometry

Dimensions that vary from humanoid dimensions are considered ease.[40] Ease may be either negative (less than humanoid dimensions) or positive (more than humanoid dimensions). Negative ease compresses and redistributes body tissue. Positive ease creates an airgap between the human and cover or humanoid and coveroid.[28] In virtual environments, ease may be measured as compression ease (force exerted on body from fabric [41]) or radial ease (offset from body creating an airgap).

Assuming the above hypothesis on body-shape has been established, we can now consider how ease is added to create to coveroid geometry. Since ease can be both negative and positive, negative ease could be accomplished through either the addition of a dart beyond those established as 2D body shape, or the application of negative geometry to a seam. Positive ease would be the inverse activity, releasing a dart for use as ease or the application of positive ease to a seam.

3.3. Considering the Future for Cover and Coveroid Sizing

Since current RTW offers adequate fit results utilizing mainly fit tolerance strategy, the opportunity for body-shape sizing combined with quantified fit tolerance strategy to radically improve RTW fit is very real. This is strongly supported by past study demonstrating the potential for improved fit with sizing aimed at specific body-shape categories.[19] This also offers much opportunity for the optimization of made-to-measure (MTM), a long sought-after goal of apparel digitization.

3.4. Considering the Future for Fit Assessment

Regardless of improved pattern-engineering practice size selection applications must be capable of matching consumer subjective opinion to objective geometric dimension. [42] Ultimately, this will mean delivering customer product which a brand’s fit algorithms have deemed unsuitable. Fit is and always will be subjective to the wearer, even if it can be objectively measured in manufacture. Assessing fit must reconcile how any given fit situation, even when quantified, may be assessed differently by wearer, observer, designer, and pattern-engineer. For such assessments to be made possible, measurable fit intent must become an integral part of the digital tech pack.

Within traditional apparel practice, the reuse of child patterns as template blocks creates a situation where a quantification of fit is difficult, if not impossible. Shaping devices, hidden within design lines and ease, are indeed in many cases unquantifiable without reference to the parent block. Within virtual environments, however, there exists much opportunity to maintain reference to the parent block. For example, if a decision were made to delegate all fit related decisions to the parent block, this fit data (quantified as geometric dimension) could be included as digital tech pack data passed to all pattern family iterations (child, grandchild, etc.).

The evolution of the tech pack to be digitally linked to the coveroid offers the possibility to evolve fit intent for relevance as both artistic and mathematical descriptors of fit. If confirmed, the original goals of mass customization could be conceptualized as geometric pattern dimension comprised of fit preference and body-shape data sets. Further study should test the possibility of quantifying body-shape as 2D pattern geometry.

4. Conclusion

Here we have discussed terminology common to apparel fit practices within the framework of the 3DBP ecosystem. From this common ground the fit language is made accessible to the varied user base now involved in developing cover and coveroid products and the 3DBP technologies supporting this development. Through this discussion, apparel fit challenges can be discussed relative to both physical and virtual space practice and suitable for both the perspective of the apparel practitioner (requiring subjective, heuristic, sensory processes) and the software architect (requiring objective, logical processes). From this clarity, a path forward for quantified apparel fit practice emerges and the adoption of 3DBP technologies can be considered from the perspective of matching application to required data sets.

With the apparel industry transitioning from single use poor fitting garment purchase practice to “conscious consumerism,” expectations regarding fit will rise. Garments that fail to meet customer expectations regarding fit are returned. Returned garments defeat gains achieved with on-demand manufacturing. Fit strategies, affecting all consumer buying decisions could very well be the force making other sustainability initiatives viable. From both a conscious consumer and revenue optimization perspective quantified fit strategy is worthy of further study, seeing RTW, MTM, and bespoke as integral apparel offerings toward a more sustainable 3DBP apparel ecosystem. The success of these rest on the ability to use technologies to enhance the engineering of garments.

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